

ABSTRACT

A microactuator according to the present invention comprises a base 1, a movable section 7 which is capable of displacement relative to the base 1, an elastic supporting member 5 for supporting the movable section 7, and driving sections 4a to 4c for causing the movable section 7 to be displaced. A specific relationship is imposed on a spring modulus responsive to a displacement of the movable section 7 along a vertical direction and a spring modulus responsive to a tilt angle of the movable section 7, and the diagonality between the driving force and the displacement of the movable section 7 is increased, thus realizing accuracy improvements and simplification of control of the microactuator.